

HITACHI
Inspire the Next

VARIABLE FREQUENCY DRIVE

SJ700 & SJ700B series

*Powerful Inverter
with Sensorless Vector Control*



For More Precise Control



For General Purpose Use

1 Dual rating

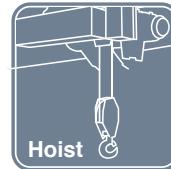
- SJ700D can be used for both heavy and normal duty.
- One-frame-size smaller SJ700D may be applicable for variable torque applications.



SJ700
SJ700D-150LFF3
(15kW)

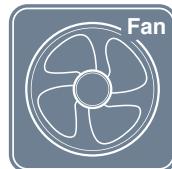
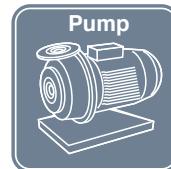
Heavy duty:

→ **15kW**
(overload capacity:150%,60sec)



Nominal duty:

→ **18.5kW**
(Overload capacity:120%,60sec)



2 EzSQ improvement (1task/2ms⇒5 tasks/2ms)

- By separating codes to be repeated as loops in different tasks, overall execution can be faster.

3 RS485 (Modbus-RTU) communication speed is improved (Max19.2kbps⇒115.2kbps speed is improved)

- Approx. 6 times faster communication in comparison with the prior model is now supported.
Additionally, more communication commands are available.

4 LCD operator (Optional:WOP) upgrade

- 5-line LCD operator
- Real time clock built in
- 4 sets of user parameter configurations can be saved and transferred.
- Two color backlight that distinguishes trip status
- User selectable content for display.



5 Versatile functions

- Phase loss input protection : covers not only the input but output as well.
- Automatic return to the initial display (b164):
Without operating for 10 minutes, the display returns to the initial display automatically.



The Hitachi SJ700D-3 series succeed the SJ700-2 series with the additional and enhanced features

6 Induction motor & permanent magnetic motor control with one inverter (PM motor control : ordering production)

- The SJ700D series inverter can drive both induction motors (IM) and permanent magnetic motors (PM).



Details of enhancement (Comparison between SJ700-2 and SJ700D-3)

No.	item	Enhanced function, added parameters, etc.			Remarks
1	Model	SJ700D-004 to 550LFF3/LFEF3/LFUF3 SJ700D-007 to 1320HFF3/HFEF3/1500HFUF3			
2	Added function	Constant torque/ Variable torque (CT/VT) selection	Constant torque / Variable torque mode selectable (b049)	Newly added parameter b049 to switch between Constant torque mode and Variable torque mode.	In case of driving light load application, you can choose one power size smaller inverter or one frame size smaller inverter.
3		PM motor control [ordering production]	Control mode (A044)	PM motor control (06) is added to the selection in A044	PM motor control is only available in Variable torque mode. (note) The model supporting PM motor control is ordering production.
4			PM motor control parameters (H101~H134)	Parameters related to PM motor control are newly added (same as WJ200 series)	
5		Automatic return to the initial display	Automatic return to the initial display (b164)	Without operating for 10 minutes, the display returns to the initial display automatically.	
6		Data read and write	Data Read/Write selection (b166)	Selection of enabling or disabling data Read / Write from the copy unit WOP for parameter setting protection and security	
7		Inverter mode	Inverter mode monitor (d060)	Displays currently selected inverter mode, IM motor (induction motor) or PM motor mode.(IM mode or PM mode.)	
8		Phase loss protection	Phase loss output protection (b141,b142)	The inverter detects motor output phase loss	
9		EzSQ	Improvement	Parallel processing of 5 tasks	
10				EzSQ starting trigger terminal: changed from FW terminal to PRG terminal which can be assigned any of input terminals.	
11			Additional function	Always running mode is added to selection of starting method for EzSQ.	
12				Command to store changed data into EEPROM (eepwrt command)	
13				Command to obtain clock data from WOP (rtcset command)	
14				Part of EzSQ program variables (P129 (U29) to P131 (U31)) are automatically stored at power down (only when A017 is other than 00)	
15		WOP operator [Option]	Full compatibility with the copy unit WOP(5 line display)		
16			Real time clock function is available.		
17	Improvement function	RS485	Communication speed is improved.	2400/4800/9600/19.2k/38.4k/57.6k/76.8k/115.2k bps	
18			Modbus RTU	Maximum data length is expanded. 03h (Read holding register) 10h (Write in holding registers)	4 registers (8 byte) to 16 registers (32 byte)
19				Command to write into/read from multiple holding registers is added (17h: Write/Read multiple holding registers)	Read and Write 16 registers (32 byte)
20				Broadcast communication function is added.	
21				EEPROM storing mode is added.	
22		Initializing	Initializing method	Parameter setting (b180=01) triggers initialization	Initialization method of SJ700-2 is also valid.
23			Initializing of EzSQ	Parameter b084 range is expanded.	
24			Initial value	b037=00 (Full access)	
25		Selection of initial display	Selection of initial display is expanded (all monitoring parameters, frequency command F001 (WOP monitor B)		
26	Others	Warnings	Warnings are organized.		
27		Run command in case of warnings	At occurrence of warning, the inverter does not accept Run		



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Series
Line up

SJ700

For More Precise Control



SJ700B

For General Purpose Use



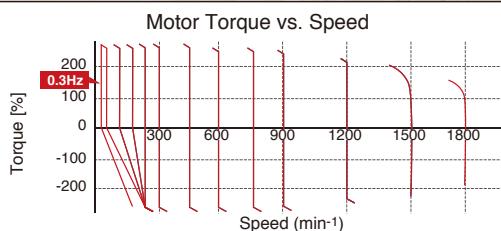
High starting torque, Powerful drive and easy setting

High starting torque

Improved sensorless vector control and auto tuning produce high starting torque of 200% or more at 0.3Hz.*¹

Easy setup of motor constants

Ideal for applications which need high torque, such as cranes, extruders and lifts.



*¹ Starting torque

Series	Applicable motor	Starting torque
SJ700D(CT)	0.4 to 55kW	0.3Hz/200%
	75 to 132kW	0.3Hz/180%
SJ700	185 to 400kW	0.3Hz/150%
SJ700B	11 to 75kW	0.5Hz/150%
	90 to 160kW	0.5Hz/120%

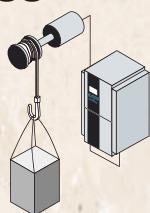
Possible with SJ700 series

Hitachi exclusive 0Hz domain sensorless vector control^{*)}

Develops 150% (SJ700B:120%)*² torque at 0Hz speed reference

Ideal for cranes and other applications that require high torque upon starting.

*² when inverter is one frame size larger than motor.

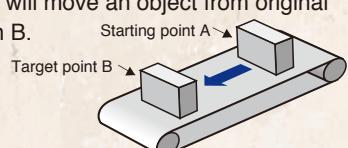


Position control function^{*)}

The SJ700D/SJ700/SJ700B, with optional feedback board installed, together with an encoder-equipped motor can perform position control.

For many applications, suitable performance can be achieved at a lower cost than servo systems.

Based on your four motion parameters (position command, speed command, acceleration time and deceleration time), the SJ700D/SJ700/SJ700B will move an object from original position A to target position B.



After the movement, the inverter keeps hold motor position.

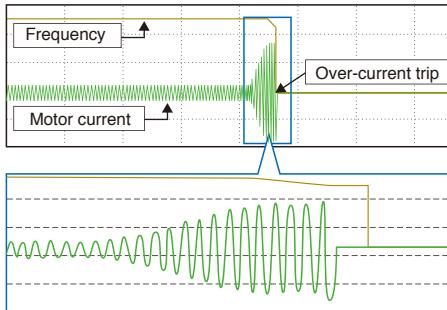
^{*)} Derating is applied for SJ700B. Please consult technician at Hitachi or its distributor before use.

Trip avoidance function

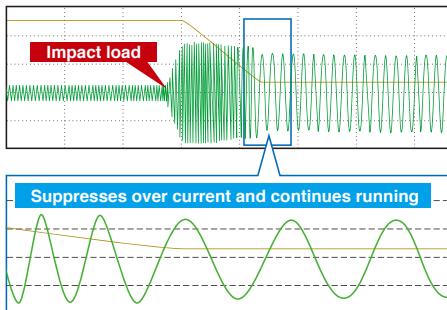
Over current & voltage suppress function

Higher internal calculation speed improves current control performance.

Over-current suppress and Over-voltage suppress functions avoid inverter trips during acceleration and deceleration.



Over-current suppress OFF

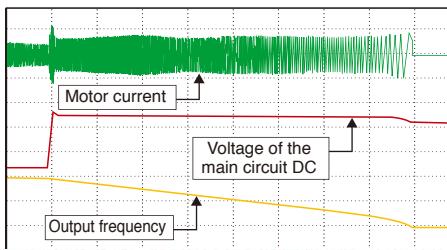


Suppresses over current and continues running

Over-current suppress ON

DC bus AVR function during deceleration

The SJ700D/SJ700/SJ700B controls deceleration time so that the DC bus voltage does not exceed the over-voltage trip level, providing trip-less operation during deceleration.



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High performance, powerful functions, yet user friendly.

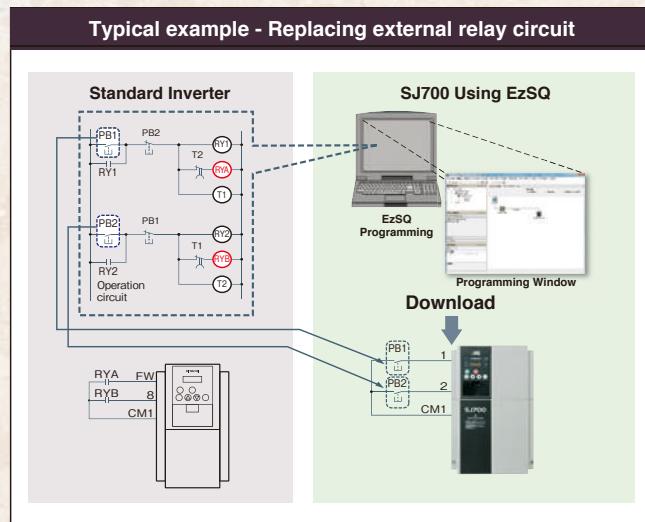
Programming [EzSQ: easy sequence] function

Inverter control by built-in programming functions

Custom operation is realized by downloading to an inverter a user program created with ProDriveNext, Hitachi inverter configuration software.

Tailor inverter operation to meet changing process requirements, and replace separate PLCs in some cases. By simplifying or eliminating external hardware, significant cost savings can be achieved.

Password function is incorporated to provide security for proprietary program data against loss or unauthorized modification.



Item	Description	
Language Spec	Language type	BASIC Like
	Supported Device	Windows (DOS/V)OS:WindowsVista, Windows7)
	Memory area	1,024 steps or 6k byte (Smaller of these)Program is stored in internal of inverter.
	Programming environment	Editor (Windows), Display (Windows) Syntax check (Windows)
	Executable format	Program download/upload, All clear Interpreter 2.0ms/command (Sub routine supported. 8 nested)
I/O function	External input	Contact signal/Open collector signal input (Internal DC24V power supply available)
		External digital contact input
		Program RUN SJ700D:PRG terminal SJ700/SJ700B:FW terminal
	External analog input	General-purpose input
		Maximum of 8 point (X(00)-X (07))
		XA (0) : 0-10V (O terminal)
	External output	XA (1) : 4-20mA (OI terminal)
		XA (2) : 0-10V (O2 terminal)
		General-purpose output terminal
Command	Maximum of 6 point (Y (00)-Y (05))	
	YA (0) : Setup for FM terminal is possible.	
	YA (1) : Setup for AM terminal is possible.	
	YA (2) : Setup for AML terminal is possible.	
	Programmable flow control <Loop, Unconditional jump, conditional jump, Time control, Sub routine, Others>	
Reserved word	Operation command <+, -, *, /, substitution, mod, abs>	
	I/O control (Bit input, Word input, Bit output, Word output)	
	Timer control <on delay, off delay>	
	Inverter parameter setting	
	User	U (00)-U (31)/32 point
	Timer	UL (00)-UL (07)/8 point
	Set frequency	SET-Freq
	Acceleration time	ACCEL
	Deceleration time	DECEL
	Monitor	Output frequency, Output current, Rotation direction, PID feedback, Converted frequency, Output torque, Output voltage, Power, Cumulative RUN time, Cumulative power-on time, trip
* Windows® is a registered trademark of Microsoft Corporation.U.S.A and other countries.		

EMC Filter & brake circuit integrated as standard

Built-in EMC filter up to 150kW*

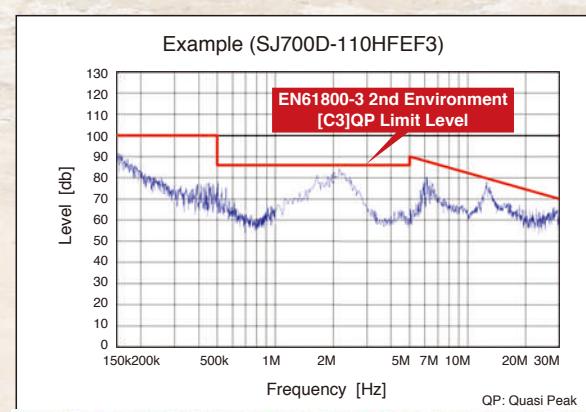
Cost and space reduction compared with external EMC filter.
Reduces electromagnetic noise.Meets EN61800-3 2nd-Environment

* SJ700: European Version and Japanese Version does not have 150 kW
SJ700B: All models (5.5kW is without EMC Filter)

Built-in brake resistor circuit up to 22kW*

Cost and space reduction compared with external braking controller.

* SJ700B: Up to 30kW



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Ease of maintenance

Easy-removable construction for maintenance

Field replacement of cooling fan (s) and DC bus capacitors can be accomplished in a fraction of the time.

Using Logic terminal move to SJ700D/SJ700 without wiring change.

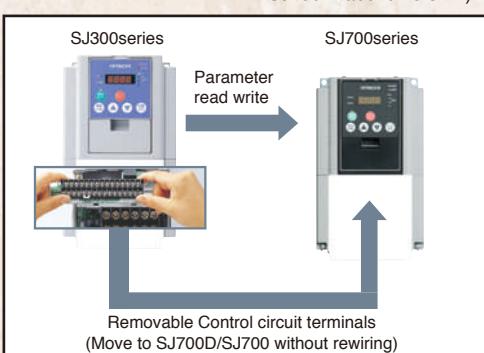
Read SJ300 Parameter by WOP remote operator and write them in to SJ700D/SJ700



Easy-removable Cooling Fan



Easy-removable DC bus Capacitors
(SJ700D/SJ700: above 15kW
SJ700B: above 18.5kW)



*1 Control circuit terminals comparison table

Series	Input terminals	Output terminals
SJ700D/SJ700	9 terminals (Intelligent 8terminals,FW)	5 terminals (Open collector outputs)
SJ700B		
SJ300		
L300P	6 terminals (Intelligent 5terminals,FW)	2 terminals (Relay outputs)

Long lifetime components & Lifetime warning function

Long lifetime components

Design lifetime 10 Years or more for DC bus capacitors & Cooling Fan. Cooling Fan ON/OFF control function for longer fan life.

*Condition for lifetime calculation -

Ambient temperature: 40 deg C (SJ700B: 30 deg C)

Ambient condition: No corrosive gas, oil mist nor dust

10 years is a design lifetime base on calculation, and not guaranteed

Lifetime warning function

Lifetime warning function helps to perform preventive maintenance before a failure occurrence.

DC bus capacitor, cooling fan, heat sink temperature and motor temperature can be monitored in order to replace components prior to failure.

Easy operation

User selection of displayed parameters

Data comparison display mode

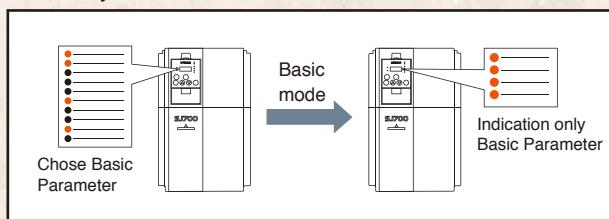
Displays only parameters changed from factory default

User-defined parameter display mode

Displays only user defined parameters
(up to 12 parameters, U001 to U012)

Basic parameter display mode

Displays only pre-defined basic parameters which are used commonly



Other functions

Direct digit edit mode for quicker selection of parameter.
Returning to output frequency monitor display (d001) by holding the FUNC key for 3 seconds regardless of the current content.

Network compatibility

The Modbus-RTU communication is embedded as standard along with a dedicated terminal.

Other fieldbus communications such DeviceNet and PROFIBUS-DP are supported with optional fieldbus modules.

-DeviceNet is a trade mark of Open DeviceNet Vender Association, Inc.

-PROFIBUS-DP is a registered trade mark of PROFIBUS Nutzer Organization

Simple & Low cost wiring, ease of installation and replacement using fieldbus communication



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Global standards

Conformity to global standards

CE, UL, c-UL, C-Tick approvals.



Logic input & output terminal apply sink & source logic

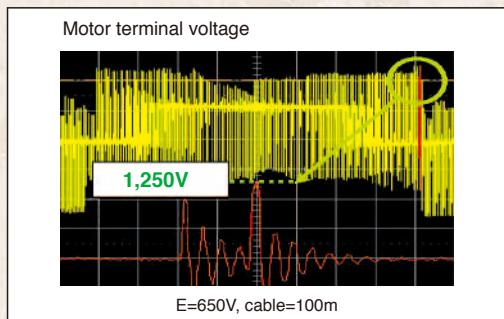
Wide Input power voltage range

Input voltage 240V for 200V class and 480V for 400V class as standard.

Environmental friendliness

Micro surge voltage suppress function

Hitachi original PWM control method limits motor terminal voltage to less than two times of inverter DC bus voltage. Lower than Hitachi motor Max. insulation voltage (1,250V) (During regeneration, the motor terminal voltage may exceed the motor maximum insulation voltage (1,250V))



EU RoHS compliant

EU RoHS compliant (except solder in power module)

Improvement of environmental tolerance

Varnish coating of internal PC board & plating of main circuit copper bus bar are standard.

Versatile functions

Instantaneous power failure disregard function

The SJ700D/SJ700/SJ700B overrides instantaneous power failure when power fluctuation happens frequently, as long as DC bus voltage remains higher than under-voltage trip level.

Emergency stop

Shuts down the inverter by hardware, bypassing the CPU, to achieve a reliable, emergency stop function.

Intelligent input terminal and output terminal ON/OFF delay function

Helps simplify external circuits.

Active frequency matching function

Motor frequency match restart function operates effectively even without motor residual voltage.

Controlled deceleration and stop on power loss

Analog input disconnection detection function

The SJ700D/SJ700/SJ700B outputs a disconnection signal when frequency command through analog input is lost.

Acceleration/Deceleration curve functions

The curve shape (five types, such as S-curve, etc.) can be chosen according to the application requirements.

Analog command holding function (AHD)

Output frequency can be changed with UP/DOWN Function, or with an analog signal as reference value. The set frequency at power shutdown can be saved, too.

Pulse train input function

Pulse train input for Frequency reference or PID feed back signal, with SJ-FB (speed feed back card option).

Integrated input electric power monitor

Input electric power (kW) and Integrated input electric power for monitoring energy saving.

Automatic carrier frequency adjustment function

The SJ700D/SJ700/SJ700B detects motor current and automatically reduces carrier frequency according to the current.

The resolution of analog outputs (voltage, current) is improved to 10 bits.



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SPECIFICATIONS

● General Specifications

Items		General Specifications						
Control	Control method	Line to line sine wave pulse-width modulation (PWM) control						
	Output frequency range (*6)	0.1-400.0Hz(400kW:0.1-120Hz)						
	Frequency accuracy	Digital: ±0.01% of the maximum frequency, Analog: ±0.2%(25±10°C)						
	Frequency resolution	Digital setting: 0.01Hz, Analog setting: (Maximum frequency)/4,000 (O terminal: 12bit 0-10V, O2 terminal: 12bit -10+10V)						
	V/f characteristics	SJ700D:IM : V/f optionally variable (30-400Hz of base frequency), V/f control (constant torque, reduced torque), sensorless vector control,0Hz ranged sensorless vector control (only CT), vector with sensor (SJ-FB card option , only CT) [ordering production] PM : sensorless vector control (only VT) SJ700/SJ700B:IM : V/f optionally variable (30-400Hz of base frequency), V/f control (constant torque, reduced torque), sensorless vector control 0Hz ranged sensorless vector control, vector with sensor (SJ-FB card option)						
	Speed fluctuation	±0.5% (sensorless vector control)						
	Acceleration/deceleration time	0.01-3,600sec. (Linear/curve, accel./decel. selection), Two-stage accel./decel.						
	Starting Torque	<table border="1"> <tr> <td>SLV</td><td>SJ700/SJ700D (CT) 200%/0.3Hz, (VT) 150%/0.5Hz, 75kW to 150kW (CT) 180%/0.3Hz, (VT) 120%/0.5Hz, 185kW and over 150%/0.3Hz. SJ700B : 150%/0.5Hz, 90kW and over : 120%/0.5Hz,</td></tr> <tr> <td>0Hz-SLV</td><td>SJ700/SJ700D (CT) (0Hz domain with motor one frame size down) 150% at around 0Hz, 75kW and over: 130% at around 0Hz. SJ700B : 120% at around 0Hz,SJ700D (VT):Disable.</td></tr> <tr> <td>PM-SLV[ordering production]</td><td>SJ700D (0.4 to 132kW) : 50% (at 10% of motor constant speed) [ordering production] (only SJ700D (VT))</td></tr> </table>	SLV	SJ700/SJ700D (CT) 200%/0.3Hz, (VT) 150%/0.5Hz, 75kW to 150kW (CT) 180%/0.3Hz, (VT) 120%/0.5Hz, 185kW and over 150%/0.3Hz. SJ700B : 150%/0.5Hz, 90kW and over : 120%/0.5Hz,	0Hz-SLV	SJ700/SJ700D (CT) (0Hz domain with motor one frame size down) 150% at around 0Hz, 75kW and over: 130% at around 0Hz. SJ700B : 120% at around 0Hz,SJ700D (VT):Disable.	PM-SLV[ordering production]	SJ700D (0.4 to 132kW) : 50% (at 10% of motor constant speed) [ordering production] (only SJ700D (VT))
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PM-SLV[ordering production]	SJ700D (0.4 to 132kW) : 50% (at 10% of motor constant speed) [ordering production] (only SJ700D (VT))							
Carrier frequency range	SJ700/SJ700D (CT) 0.5 to 15kHz, (VT) 0.5 to 12 kHz, 75kW to 150kW (CT) 0.5 to 10kHz, (VT) 0.5 to 8 kHz, 185kW and over : 0.5 to 3.0kHz SJ700B : 0.5 to 12.0kHz (90kW and over : 0.5 to 8.0kHz)							
DC braking	Performs at start: under set frequency at deceleration, via an external input (braking force, time, and operating frequency).							
Input signal	Frequency setting	<table border="1"> <tr> <td>Operator</td><td>Up and Down keys</td></tr> <tr> <td>External signal(*8)</td><td>DC 0-10V, -10+10V (input impedance 10kΩ), 4-20mA (input impedance 100Ω)</td></tr> <tr> <td>External port</td><td>Setting via RS485 communication</td></tr> </table>	Operator	Up and Down keys	External signal(*8)	DC 0-10V, -10+10V (input impedance 10kΩ), 4-20mA (input impedance 100Ω)	External port	Setting via RS485 communication
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Forward /reverse Start /stop	<table border="1"> <tr> <td>Operator</td><td>Start/stop commands (forward/reverse switching by parameter setting)</td></tr> <tr> <td>External signal</td><td>Forward-operation start/stop commands (reverse-operation start/stop possible when relevant commands are assigned to intelligent input terminals)3-wire input possible (when relevant commands are assigned to control circuit terminals)</td></tr> <tr> <td>External port</td><td>Setting via RS485 communication</td></tr> </table>	Operator	Start/stop commands (forward/reverse switching by parameter setting)	External signal	Forward-operation start/stop commands (reverse-operation start/stop possible when relevant commands are assigned to intelligent input terminals)3-wire input possible (when relevant commands are assigned to control circuit terminals)	External port	Setting via RS485 communication	
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External signal	Forward-operation start/stop commands (reverse-operation start/stop possible when relevant commands are assigned to intelligent input terminals)3-wire input possible (when relevant commands are assigned to control circuit terminals)							
External port	Setting via RS485 communication							
Intelligent input terminals	<table border="1"> <tr> <td>Terminals</td><td>8 terminals, NO/NC switchable, sink logic/source logic switchable</td></tr> <tr> <td>Functions</td><td>Reverse operation (RV), Multi-speed 1 setting (CF1), Multi-speed 2 setting (CF2), Multi-speed 3 setting (CF3), Multi-speed 4 setting (CF4), Jogging (JG), external DC braking (DB), 2nd motor control (SET), 2-stage acceleration/deceleration (2CH), free-run stop (FRS), external trip (EXT), unattended start protection (USP), commercial power supply switching (CS), software lock (SFT), analog input switching (AT), 3rd motor control (SET3), reset (RS), starting by 3-wire input (STA), stopping by 3-wire input (STP), forward/reverse switching by 3-wire input (F/R), PID disable (PID), PID integration reset (PIDC), control gain switching (CAS), acceleration by remote control (UP), deceleration by remote control (DOWN), data clearance by remote control (UDC), forcible operation (OPE), Multi-speed bit 1 (SF1), Multi-speed bit 2 (SF2), Multi-speed bit 3 (SF3), Multi-speed bit 4 (SF4), Multi-speed bit 5 (SF5), Multi-speed bit 6 (SF6), Multi-speed bit 7 (SF7), overload restriction selection (OLR), torque limit selection (enabling/disabling) (TL), torque limit 1 (TRQ1), torque limit 2 (TRQ2), P/PI switching (PPI), braking confirmation (BOK), orientation (ORT), LAD cancellation (LAC), clearance of position deviation (PCLR), permission of 90°shift phase (STAT), trigger for frequency addition (A145) (ADD), forcible-terminal operation (F-TM), permission of torque command input (ATR), cumulative power clearance (KHC), servo-on (SON), pre-excitation (FOC), general-purpose input 1 (MI1), general-purpose input 2 (MI2), general-purpose input 3 (MI3), general-purpose input 4 (MI4), general-purpose input 5 (MI5), general-purpose input 6 (MI6), general-purpose input 7 (MI7), general-purpose input 8 (MI8), analog command holding (AHD), Multistage position settings selection 1 (CP1), Multistage position settings selection 2 (CP2), Multistage position settings selection 3 (CP3), Zero-return limit function (ORL), Zero-return trigger function (ORG), Forward drive stop (FOT), reverse drive stop (ROT), Speed / position switching (SPD), Pulse counter (PCNT), Pulse counter clear (PCC), Emergency stop (EMR) ,EzSQ PRG-Run(PRQ)(*12) ,no assignment (no)</td></tr> </table>	Terminals	8 terminals, NO/NC switchable, sink logic/source logic switchable	Functions	Reverse operation (RV), Multi-speed 1 setting (CF1), Multi-speed 2 setting (CF2), Multi-speed 3 setting (CF3), Multi-speed 4 setting (CF4), Jogging (JG), external DC braking (DB), 2nd motor control (SET), 2-stage acceleration/deceleration (2CH), free-run stop (FRS), external trip (EXT), unattended start protection (USP), commercial power supply switching (CS), software lock (SFT), analog input switching (AT), 3rd motor control (SET3), reset (RS), starting by 3-wire input (STA), stopping by 3-wire input (STP), forward/reverse switching by 3-wire input (F/R), PID disable (PID), PID integration reset (PIDC), control gain switching (CAS), acceleration by remote control (UP), deceleration by remote control (DOWN), data clearance by remote control (UDC), forcible operation (OPE), Multi-speed bit 1 (SF1), Multi-speed bit 2 (SF2), Multi-speed bit 3 (SF3), Multi-speed bit 4 (SF4), Multi-speed bit 5 (SF5), Multi-speed bit 6 (SF6), Multi-speed bit 7 (SF7), overload restriction selection (OLR), torque limit selection (enabling/disabling) (TL), torque limit 1 (TRQ1), torque limit 2 (TRQ2), P/PI switching (PPI), braking confirmation (BOK), orientation (ORT), LAD cancellation (LAC), clearance of position deviation (PCLR), permission of 90°shift phase (STAT), trigger for frequency addition (A145) (ADD), forcible-terminal operation (F-TM), permission of torque command input (ATR), cumulative power clearance (KHC), servo-on (SON), pre-excitation (FOC), general-purpose input 1 (MI1), general-purpose input 2 (MI2), general-purpose input 3 (MI3), general-purpose input 4 (MI4), general-purpose input 5 (MI5), general-purpose input 6 (MI6), general-purpose input 7 (MI7), general-purpose input 8 (MI8), analog command holding (AHD), Multistage position settings selection 1 (CP1), Multistage position settings selection 2 (CP2), Multistage position settings selection 3 (CP3), Zero-return limit function (ORL), Zero-return trigger function (ORG), Forward drive stop (FOT), reverse drive stop (ROT), Speed / position switching (SPD), Pulse counter (PCNT), Pulse counter clear (PCC), Emergency stop (EMR) ,EzSQ PRG-Run(PRQ)(*12) ,no assignment (no)			
Terminals	8 terminals, NO/NC switchable, sink logic/source logic switchable							
Functions	Reverse operation (RV), Multi-speed 1 setting (CF1), Multi-speed 2 setting (CF2), Multi-speed 3 setting (CF3), Multi-speed 4 setting (CF4), Jogging (JG), external DC braking (DB), 2nd motor control (SET), 2-stage acceleration/deceleration (2CH), free-run stop (FRS), external trip (EXT), unattended start protection (USP), commercial power supply switching (CS), software lock (SFT), analog input switching (AT), 3rd motor control (SET3), reset (RS), starting by 3-wire input (STA), stopping by 3-wire input (STP), forward/reverse switching by 3-wire input (F/R), PID disable (PID), PID integration reset (PIDC), control gain switching (CAS), acceleration by remote control (UP), deceleration by remote control (DOWN), data clearance by remote control (UDC), forcible operation (OPE), Multi-speed bit 1 (SF1), Multi-speed bit 2 (SF2), Multi-speed bit 3 (SF3), Multi-speed bit 4 (SF4), Multi-speed bit 5 (SF5), Multi-speed bit 6 (SF6), Multi-speed bit 7 (SF7), overload restriction selection (OLR), torque limit selection (enabling/disabling) (TL), torque limit 1 (TRQ1), torque limit 2 (TRQ2), P/PI switching (PPI), braking confirmation (BOK), orientation (ORT), LAD cancellation (LAC), clearance of position deviation (PCLR), permission of 90°shift phase (STAT), trigger for frequency addition (A145) (ADD), forcible-terminal operation (F-TM), permission of torque command input (ATR), cumulative power clearance (KHC), servo-on (SON), pre-excitation (FOC), general-purpose input 1 (MI1), general-purpose input 2 (MI2), general-purpose input 3 (MI3), general-purpose input 4 (MI4), general-purpose input 5 (MI5), general-purpose input 6 (MI6), general-purpose input 7 (MI7), general-purpose input 8 (MI8), analog command holding (AHD), Multistage position settings selection 1 (CP1), Multistage position settings selection 2 (CP2), Multistage position settings selection 3 (CP3), Zero-return limit function (ORL), Zero-return trigger function (ORG), Forward drive stop (FOT), reverse drive stop (ROT), Speed / position switching (SPD), Pulse counter (PCNT), Pulse counter clear (PCC), Emergency stop (EMR) ,EzSQ PRG-Run(PRQ)(*12) ,no assignment (no)							
Thermistor input	1 terminal (PTC characteristics)							
Intelligent output terminals	<table border="1"> <tr> <td>Terminals</td><td>5 open-collector output terminals, NO/NC switchable, sink logic/source logic switchable 1 relay (1c-contact) output terminal: NO/NC switchable</td></tr> <tr> <td>Functions</td><td>Running (RUN), constant-speed reached (FA1), set frequency overreached (FA2), overload notice advance signal (1) (OL), output deviation for PID control (OD), alarm signal (AL), set frequency reached (FA3), over-torque (OTQ), instantaneous power failure (IP), undervoltage (UV), torque limited (TRQ), operation time over (RNT), plug-in time over (ONT), thermal alarm signal (THM), brake release (BRK), 0Hz detection signal (ZS), speed deviation maximum (DSE), positioning completed (POK), set frequency overreached 2 (FA4), set frequency reached 2 (FA5), overload notice advance signal (2) (OL2), PID feedback comparison (FBV), communication line disconnection (NDc), logical operation result 1 (LOG1), logical operation result 2 (LOG2), logical operation result 3 (LOG3), logical operation result 4 (LOG4), logical operation result 5 (LOG5), logical operation result 6 (LOG6), capacitor life warning (WAC)(*11), cooling-fan speed drop (WAF), starting contact signal (FR), heat sink overhear warning (OHF), low-current indication signal (LOC), general-purpose output 1 (MO1), general-purpose output 2 (MO2), general-purpose output 3 (MO3), general-purpose output 4 (MO4), general-purpose output 5 (MO5), general-purpose output 6 (MO6), inverter ready (IRDY), forward rotation (FWR), reverse rotation (RVR), major failure (MJA), window comparator O (WCO), window comparator OI (WCOI), window comparator O2 (WCO2), alarm code 0 to 3 (AC0 to AC3)</td></tr> <tr> <td>Monitor output terminals</td><td>Analog voltage output, analog current output, pulse-string output (e.g., A-F, D-F [n-fold, pulse output only], A, T, V, P)</td></tr> </table>	Terminals	5 open-collector output terminals, NO/NC switchable, sink logic/source logic switchable 1 relay (1c-contact) output terminal: NO/NC switchable	Functions	Running (RUN), constant-speed reached (FA1), set frequency overreached (FA2), overload notice advance signal (1) (OL), output deviation for PID control (OD), alarm signal (AL), set frequency reached (FA3), over-torque (OTQ), instantaneous power failure (IP), undervoltage (UV), torque limited (TRQ), operation time over (RNT), plug-in time over (ONT), thermal alarm signal (THM), brake release (BRK), 0Hz detection signal (ZS), speed deviation maximum (DSE), positioning completed (POK), set frequency overreached 2 (FA4), set frequency reached 2 (FA5), overload notice advance signal (2) (OL2), PID feedback comparison (FBV), communication line disconnection (NDc), logical operation result 1 (LOG1), logical operation result 2 (LOG2), logical operation result 3 (LOG3), logical operation result 4 (LOG4), logical operation result 5 (LOG5), logical operation result 6 (LOG6), capacitor life warning (WAC)(*11), cooling-fan speed drop (WAF), starting contact signal (FR), heat sink overhear warning (OHF), low-current indication signal (LOC), general-purpose output 1 (MO1), general-purpose output 2 (MO2), general-purpose output 3 (MO3), general-purpose output 4 (MO4), general-purpose output 5 (MO5), general-purpose output 6 (MO6), inverter ready (IRDY), forward rotation (FWR), reverse rotation (RVR), major failure (MJA), window comparator O (WCO), window comparator OI (WCOI), window comparator O2 (WCO2), alarm code 0 to 3 (AC0 to AC3)	Monitor output terminals	Analog voltage output, analog current output, pulse-string output (e.g., A-F, D-F [n-fold, pulse output only], A, T, V, P)	
Terminals	5 open-collector output terminals, NO/NC switchable, sink logic/source logic switchable 1 relay (1c-contact) output terminal: NO/NC switchable							
Functions	Running (RUN), constant-speed reached (FA1), set frequency overreached (FA2), overload notice advance signal (1) (OL), output deviation for PID control (OD), alarm signal (AL), set frequency reached (FA3), over-torque (OTQ), instantaneous power failure (IP), undervoltage (UV), torque limited (TRQ), operation time over (RNT), plug-in time over (ONT), thermal alarm signal (THM), brake release (BRK), 0Hz detection signal (ZS), speed deviation maximum (DSE), positioning completed (POK), set frequency overreached 2 (FA4), set frequency reached 2 (FA5), overload notice advance signal (2) (OL2), PID feedback comparison (FBV), communication line disconnection (NDc), logical operation result 1 (LOG1), logical operation result 2 (LOG2), logical operation result 3 (LOG3), logical operation result 4 (LOG4), logical operation result 5 (LOG5), logical operation result 6 (LOG6), capacitor life warning (WAC)(*11), cooling-fan speed drop (WAF), starting contact signal (FR), heat sink overhear warning (OHF), low-current indication signal (LOC), general-purpose output 1 (MO1), general-purpose output 2 (MO2), general-purpose output 3 (MO3), general-purpose output 4 (MO4), general-purpose output 5 (MO5), general-purpose output 6 (MO6), inverter ready (IRDY), forward rotation (FWR), reverse rotation (RVR), major failure (MJA), window comparator O (WCO), window comparator OI (WCOI), window comparator O2 (WCO2), alarm code 0 to 3 (AC0 to AC3)							
Monitor output terminals	Analog voltage output, analog current output, pulse-string output (e.g., A-F, D-F [n-fold, pulse output only], A, T, V, P)							
Monitoring on display	Output frequency, output current, output torque, frequency conversion data, trip history, input/output terminal status, electric power, and others							
Other functions	Free V/f setting (7 breakpoints), frequency upper/lower limit, jump (center) frequency, acceleration/deceleration according to characteristic curve, manual torque boost level/breakpoint, energy-saving operation, analog meter adjustment, start frequency setting, carrier frequency adjustment, electronic thermal function (available also for free setting), external start/end frequency/frequency rate, analog input selection, retry after trip, restart after instantaneous power failure, output of various signals, starting with reduced voltage, overload restriction, initial-value setting, automatic deceleration at power failure, AVR function, fuzzy acceleration/deceleration, online/offline auto-tuning, high-torque multi-motor operation (*11) (sensorless vector control of two motors by one inverter)							
Protective functions	Overcurrent protection, overvoltage protection, undervoltage protection, electronic thermal protection, temperature error protection, instantaneous power failure protection, phase loss input protection, braking-resistor overload protection, ground-fault current detection at power-on, USP error, external trip, emergency stop trip, CT error, communication error, option board error, and others							
Environmental conditions	Ambient operating/storage temperature (*7)/ humidity	-10-50°C (*9) / -20-65°C / 20-90%RH (No condensation)						
	Location	Altitude 1,000m or less, indoors (no corrosive gases or dust)						
	Digital input expansion card	SJ-DG (4digits BCD, 16bits binary)						
	Feedback expansion card	SJ-FB (vector control loop speed sensor)						
Options	Network interface card	SJ-DN2 (DeviceNet (TM)) (*13), SJ-PB (T)2 (PROFIBUS) (*13)						
	Others	EMI filters, input/output reactors, radio noise filters, braking resistors, braking units, LCR filter, communication cables						

*1 : The protection method conforms to JIS C 0920 (IEC60529)

*2 : The applicable motor refers to Hitachi standard 3-phase motor (4-pole). To use other motors, be sure to prevent the rated motor current (50Hz) from exceeding the rated output current of the inverter.

*3 : The output voltage decreases as the main power supply voltage decreases except for the use of AVR function.

*4 : Braking resistor is not integrated in the inverter. Please install optional braking resistor or dynamic braking unit when large braking torque is required.

*5 : Conforms to the test method specified in JIS C 60068-2-6:2010 (IEC 60068-2-6:2007).

*6 : To operate the motor beyond 50/60Hz, please consult with the motor manufacturer about the maximum allowable rotation speed.

*7 : Storage temperature refers to the temperature in transportation.

*8 : The frequency command is the maximum frequency at 9.8V for input voltage 0 to 10VDC, or at 19.8mA for input current 4 to 20mA. If this characteristic is not satisfactory for your application, contact your Hitachi representative.

*9 : SJ700B series is -10 to 45°C. SJ700D (VT):-10 to 40°C.

*10 : Please be sure to connect DC reactor attached to 1850HF,2200HF,3150HF and 4000HF. (1850HF,2200HF and 3150HF of US/JP Version: The DC reactor is not attached.)

*11 : 1850HF,2200HF,3150HF and 4000HF: The function is not provided.

*12 : SJ700D-3 only.

*13 : The option cannot access new parameters in SJ700D-3.



EMPOWER CORPORATION (SELATAN) SDN BHD

(Co No : 150420-H) GST No : 000470700032

45 & 45A Jalan Bakawali 36, Taman Johor Jaya, 81100 Johor Bahru, Johor, Malaysia

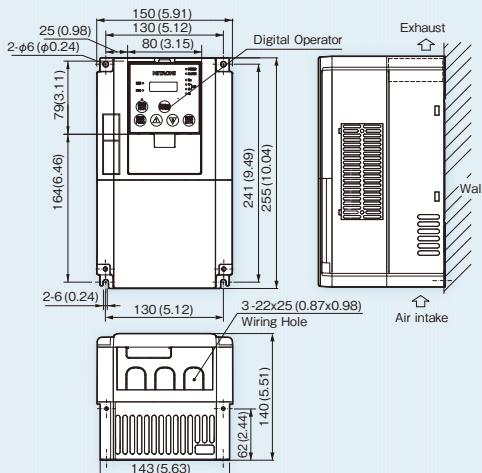
Tel : 607-3511288 (4 Lines) Fax : 607-3511292 Email : sales@empowercorp.biz

DIMENSIONS

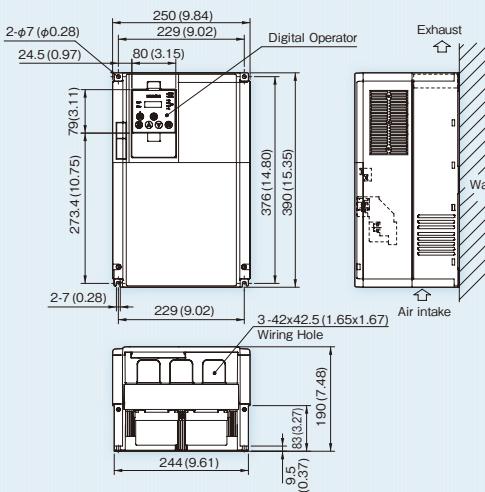
• SJ700D-004~037LFUF3,LFF3

• SJ700D-007~040HFEF3,HFUF3,007~037HFF3

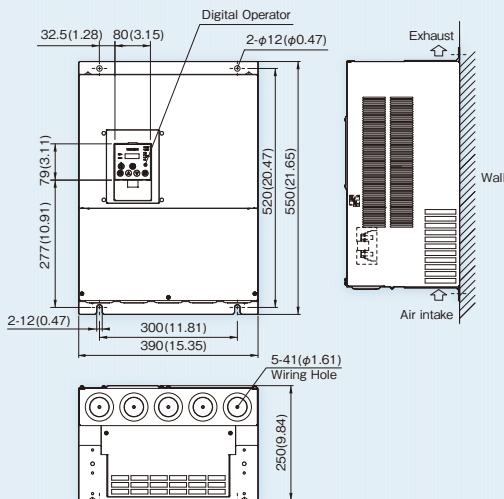
• SJ700B-055HF,055HFU



• SJ700D-150~220LFUF3,LFF3,HFEF3,HFUF3,HFF3
• SJ700B-185~300HFF,HFUF,LFUF

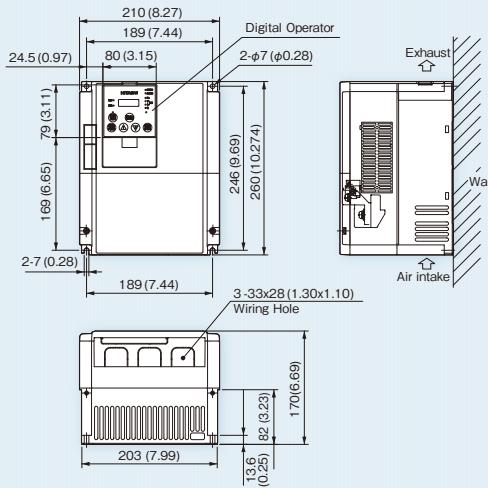


• SJ700D-370,450LFUF3,LFF3
• SJ700D-370~550HFEF3,HFUF3,HFF3
• SJ700B-450~750HFF,HFUF,450,550LFUF

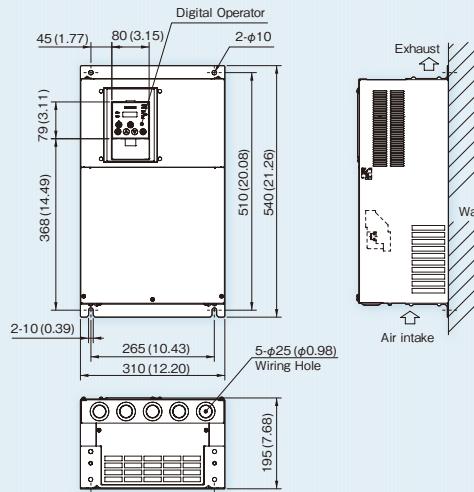


• SJ700D-055~110LFUF3,LFF3,HFEF3,HFUF3,HFF3

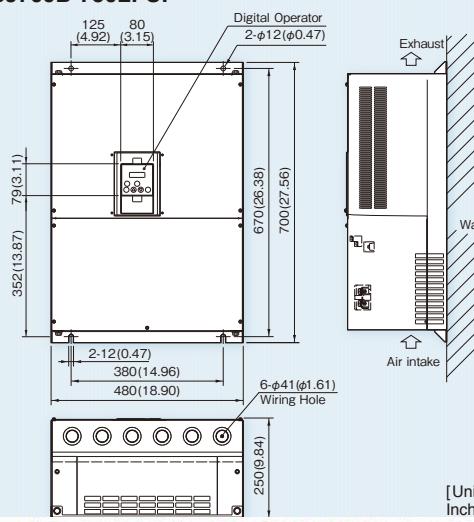
• SJ700B-075~150HFF,HFUF,LFUF



• SJ700D-300LFUF3,LFF3,HFEF3,HFUF3,HFF3
• SJ700B-370HFF,HFUF,LFUF



• SJ700D-550LFUF3,LFF3
• SJ700B-750LFUF



[Unit : mm(inch)]
Inches for reference only.

* Please refer to page 30 for detailed information about compatibility with SJ300.



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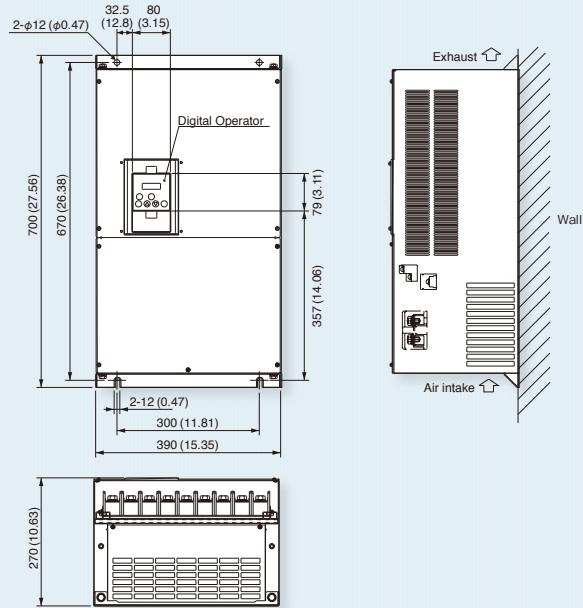
(Co No : 150420-H) GST No : 00047070032

45 & 45A Jalan Bakawali 36, Taman Johor Jaya, 81100 Johor Bahru, Johor, Malaysia

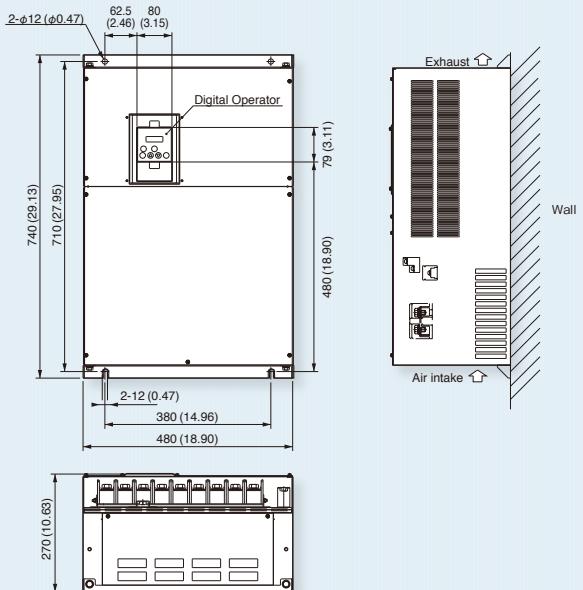
Tel : 607-3511288 (4 Lines) Fax : 607-3511292 Email : sales@empowercorp.biz

DIMENSIONS

- SJ700D-750,900HFEF3,HUFU3,HFF3
- SJ700B-900,1100HFF,HUFU



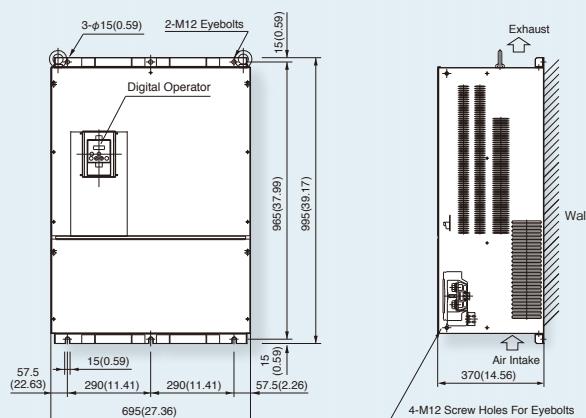
- SJ700D-1100HFEF3,HUFU3,HFF3,1320HFEF3,HFF3,1500HFUF3
- SJ700B-1320,1600HFF,HUFU



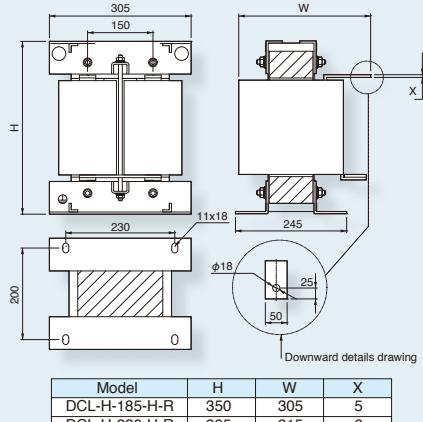
[Unit : mm(inch)]
Inches for reference only.

DIMENSIONS

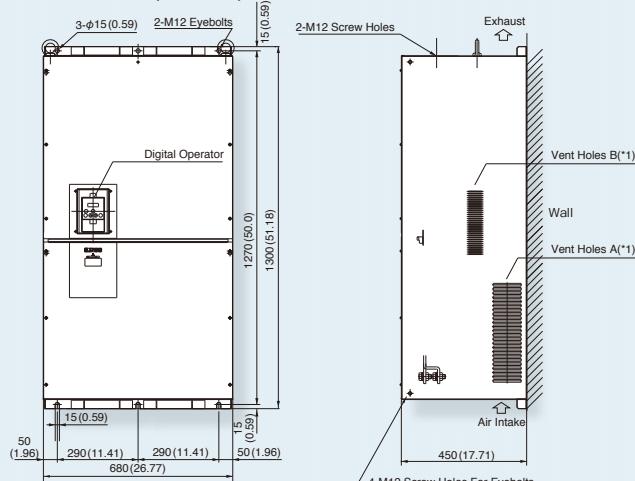
•SJ700-1850,2200HFE2,HFU2^{*2},HF2^{*2}



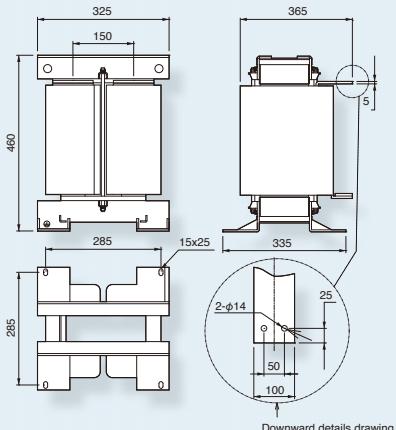
Attachment DC reactor (DCL-H-185-H-R),(DCL-H-220-H-R)



•SJ700-3150HFE2,HFU2^{*2},HF2^{*2}

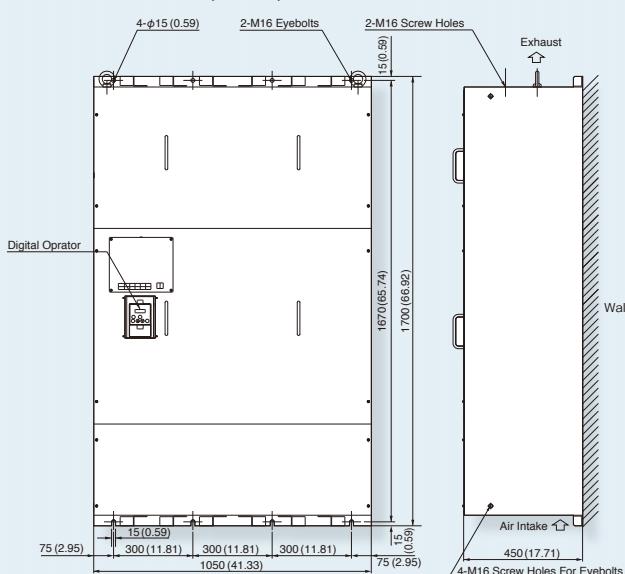


Attachment DC reactor (DCL-H-315-H-R)

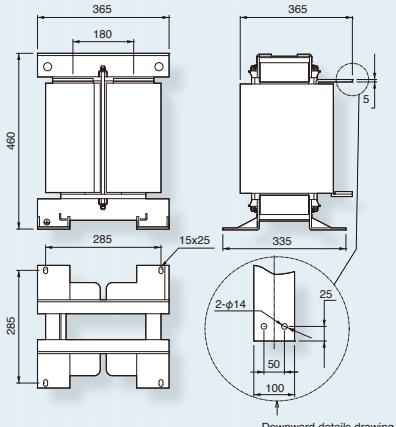


*1 Vent-Holes A are formed on both right and left side portions. Vent-Holes B are just on right side.

•SJ700-4000HFE2,HFU2,HF2



Attachment DC reactor (DCL-H-400-H-R)



^{*2} 1850H,2200H and 3150H of US/JP Version: The DC reactor is not attached.

[Unit : mm(inch)]
Inches for reference only.



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